

# Modbus RTU Protocol User Guide



**Arkon Flow Systems**  
Nováčkova 11, 614 00 Brno, Czech Republic  
Tel. +420 543 214 822, Tel./Fax +420 543 215 249  
Enquiries/ Orders/ General questions: office@arkon.co.uk  
Marketing support/ Brochures: marketing@arkon.co.uk  
Technical support: support@arkon.co.uk  
[www.arkon.co.uk](http://www.arkon.co.uk)

# List of Contents

<b>1. INTRODUCTION.....</b>	<b>2</b>
1.1 DEFINITIONS AND ABBREVIATIONS .....	2
1.2 REFERENCES .....	2
<b>2. TECHNICAL DATA .....</b>	<b>3</b>
2.1 GENERAL MODBUS RTU .....	4
<b>3. COMMISSIONING .....</b>	<b>5</b>
<b>4. MODBUS ADDRESSING MODULE .....</b>	<b>6</b>
4.1 MODBUS FUNCTION CODES.....	6
<b>5. MODBUS HOLDING REGISTERS .....</b>	<b>7</b>
5.1 PASSWORD .....	8
5.2 REAL-TIME MEASUREMENT .....	9
5.3 FLOAT REAL-TIME MEASUREMENT .....	11
5.4 INFO .....	12
5.5 DISPLAY .....	14
5.6 USER SETTINGS .....	15
5.7 EXTERNAL MEASUREMENTS .....	22
5.8 SERVICE SETTINGS .....	23
5.9 FACTORY SETTINGS .....	25
5.10 AUTHORIZE .....	27
5.11 DATALOGGER.....	28
<b>6. CONTACT.....</b>	<b>29</b>

# 1. Introduction

This manual describes the MAGX2 Modbus-RTU communication protocol.

## 1.1 Definitions and Abbreviations

<b>CRC</b>	Cyclic Redundancy Check, Used for error-checking in Modbus RTU. See appendix
<b>Modbus master</b>	A Modbus device, which is able to access data in one or more connected Modbus slaves
<b>Modbus slave</b>	A Modbus device, which is able to respond to requests from a single Modbus master
<b>Modbus address</b>	Throughout this document the following notation is used to address Modbus RTU registers: 1234 - Holding register 1234 (addressed in messages by 1233)
<b>RS232</b>	Refers to the communication standard defined by EIA/TIA-232C. (Physical layer) EIA/TIA232C
<b>USB</b>	Refers to the USB Specification usb.org
<b>RS485</b>	Refers to the 2-wire communication standard defined by EIA/TIA-485. (Physical layer)
<b>RTU</b>	Remote Terminal Unit - Standard Modbus transmission mode

## 1.2 References

<b>Reference 1</b>	<b>Modbus over Serial Line</b> Specification & Implementation guide v. 1.0 Modbus.org 12/02/02
<b>Reference 2</b>	<b>Modbus Application Protocol Specification</b> v. 1.1 Modbus.org 12/06/02
<b>Reference 3</b>	<b>MAGX2 manual</b>
<b>Reference 4</b>	<b>GSM SMS Module Specification</b>

## 2. Technical data

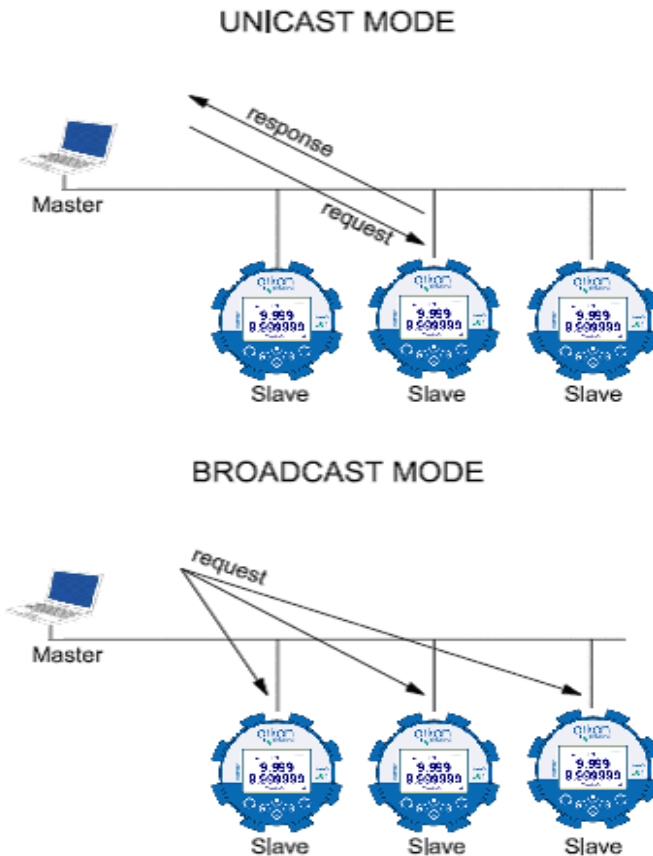
<b>ARKON Flowmeter Modbus RTU specification</b>	
<b>Device type</b>	Slave
<b>Baud rates</b>	4800, 9600, 19200, 38400 bits/sec.
<b>Number of stations Recommended:</b>	max. 31 per segment without repeaters
<b>Device address range</b>	1-247
<b>Protocol</b>	Modbus RTU (Other Modbus protocols like ASCII, Plus or TCP/IP are not supported)
<b>Electrical interface</b>	RS232, RS485 - 2 wire, USB, TCP/IP, Bluetooth
<b>Supported function code</b>	3 read holding registers
	16 write multiple registers
	17 report slave ID
<b>Broadcast</b>	No
<b>Maximum cable length</b>	Reference 3
<b>Standard Modbus over serial line v1.0)</b>	
<b>Certified</b>	No

## 2.1 General Modbus RTU

The module complies with the Modbus serial line protocol [Reference 1].

Among other things, this implies a **master-slave** protocol at level 2 of the OSI model. One node, (the master), issues explicit commands to one of the „slave“-nodes and processes responses. Slave nodes will not transmit data without request from the master node, and do not communicate with other slaves. Modbus is a mono **master system**, which means that only one **master** can be connected at any single point in time.

Two modes of communication are possible, **Unicast** and **Broadcast**. **Unicast** mode is where the **master** sends a request to one **slave device**, and waits a specified time for a response. In **Broadcast** mode the master sends out a request to address „0“, which means that the information is for all **slave devices** on the network. In **Broadcast** mode there is no response from the **slave devices**.



The Modbus frame is shown below, and is valid for both requests and responses.

SLAVE ADDRESS	FUNCTION CODE	DATA	CRC
1 Byte	1 Byte	0-252 Bytes	2 Bytes

Further details of the Modbus protocol can be found in Reference 1 and 2.

### 3. Commissioning

Before communicating with the master, Baud rate, slave ID and Parity must be selected. This can be done from the display. Please look at into the MAGX2 transmitter manual to locate the Modbus menu. (see Reference 3.)

Item	Value	Comments
<b>Slave address</b>	1 - 247	Device address [Factory setting: 1]
<b>Baud rate</b>	4800, 9600, 19200, 38400	Communication speed [Factory setting: 9600]
<b>Parity/framing</b>	Even, 1 stopbit	Communication parameters [Factory setting: Even, 1 stopbit]
	Odd, 1 stopbit	
	None, 2 stopbit	
	None, 1 stopbit	

## 4. Modbus addressing module

The module allows R/W access to the following standard Modbus data register blocks:

- Holding registers

I.e. the module will not support the other standard data register blocks:

- Coils
- „Discrete input“
- „Input registers“

### 4.1 Modbus function codes

This device supports following function codes: 3, 16 and 17.

Function code 3 and 16 are used for accessing registers. Function code 17 (report slave ID) will return a structure of identification information of the device. Below the different function code exceptions are described.

#### Function code 3 (Read holding registers)

##### General exceptions:

- Requesting less than 1 or more than 125 registers => Exception 3 (Illegal data value)
- Requesting more than max. message size => Exception 2 (Illegal data address)
- Requesting data above/crossing limitation of max. register address (0xFFFF) => Exception 2 (Illegal data address)
- If the end address is only part of a mapped holding register item (e.g. one half of a longint value) => Exception 2 (Illegal data address)

##### Application exceptions:

- Application errors => Exception 2 (Illegal data address)

##### Holes/register alignment:

- The read command always returns data if no exception is given. Bad start/end alignment will result in only parts of the data item being read.
- Holes in the holding register map return Exception 2 (Illegal data address)

#### Function code 16 (Write multiple registers)

##### General exceptions:

- Exceeding max. message size => Exception 2 (Illegal data address)
- Writing data above/crossing limitation of max. register address (0xFFFF) => Exception 2 (Illegal data address)

##### Application exceptions:

- Application errors => Exception 2 (Illegal data address)
- Application errors include writing to ReadOnly holding registers

##### Holes / register alignment:

- If start-address is not the start of a mapped holding register => Exception 2 (Illegal data address)
- Writing to holes is not allowed => Exception 2 (Illegal data address)
- If the end address is only part of a mapped holding register item (e.g. one half of a longint value), the action depends on the datatype.
- If the end address is only part of a mapped holding register item (e.g. one half of a longint value) => Exception 2 (Illegal data address)

#### Function code 17 (Report Slave ID)

- There are no exceptions for this function

## 5. Modbus holding registers

Below, the holding registers for the MAGX2 Modbus RTU module are described.

Modbus Start Register	Section
2	Password
100	Real-time measurement
150	Float real-time measurement
1000	Info
1500	Display
2000	User settings
2500	External measurements
3000	Service settings
4000	Factory settings
5000	Authorize
10000	Datalogger

### Holding registers memory map

When writing to the Holding registers, data validity is not checked. Writing incorrect values can result in unexpected behaviour of the device. In any further explanations, the following data types are used:

**Longint** – Number consisting of 32 bits, formed by 2 Modbus registers. It is necessary to write both Low and High Word of this item, the register number always has to be an even number. Not meeting these requirements will cause an Exception 2 error (Illegal data address). In case information about the number of decimals is available, then the final number is given by the following formula:  $Y = X * 10^{(-DEC)}$ , where Y is the final number, X the read number, and DEC the number of decimals.

**Bool** – this item can be read, but its value has no meaning. Writing value 1 to this item will cause an unspecified operation to be performed (erasing the Memory module, resetting the flow totalizers, etc. Reference 3). It is necessary to write both Low and High Word of this item, the register number always has to be an even number. Not meeting these requirements will cause an Exception 2 error (Illegal data address).

**Float** – IEEE 754-1985 single precision (Approximately 7 decimal digits), number consisting of 32 bits, formed by 2 Modbus registers. It is necessary to write both Low and High Word of this item, the register number always has to be an even number. Not meeting these requirements will cause an Exception 2 error (Illegal data address). Full range  $\pm 1.18 \times 10^{-38}$  to  $\pm 3.4 \times 10^{38}$ .

Modbus register	Data Type	Low/High Word
2	Longint	L
3		H
4	Bool	L
5		H
6	Float	L
7		H

### Data type memory map



## 5.1 Password

To enter the "User settings, Service settings, Factory settings, and Authorize" sections, it is necessary to enter a password in the same way as for the MAGX2 flowmeter menu, see reference 3.

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
2	1	4	Longint	0	0	9999	Password (User)	R*/W
4	3	4	Longint	0	0	999999	Password (Service)	R*/W
6	5	4	Longint	0	0	99999999	Password (Factory)	R*/W
8	7	4	Longint	0	0	99999999	Password (Authorize)	R*/W
10	9	4	Longint	0	0	9999	Password(External Measurements)	R*/W

\*) For safety purposes, it is not possible to read this item directly. In case a 0 is read from this register, it means that no valid password was entered, and the given section is not accessible. In case a 1 is read, a valid password was entered and hence the given section can be accessed freely. To close the section, you write any possible invalid password to the password entry.

**Password (User)** – default user password “1111”

**Password (External Measurements)** – default External Measurements password “1111”

## 5.2 Real-time measurement

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
100	99	4	Longint	3	-10 <sup>7</sup>	10 <sup>7</sup>	FLOW	R
102	101	4	Longint	0	0	2 <sup>32</sup>	TOTAL *	R
104	103	4	Longint	6	0	2 <sup>32</sup>	TOTAL DEC *	R
106	105	4	Longint	0	0	2 <sup>32</sup>	AUX *	R
108	107	4	Longint	6	0	2 <sup>32</sup>	AUX DEC *	R
110	109	4	Longint	0	0	2 <sup>32</sup>	TOTAL+ *	R
112	111	4	Longint	6	0	2 <sup>32</sup>	TOTAL+ DEC *	R
114	113	4	Longint	0	0	2 <sup>32</sup>	TOTAL- *	R
116	115	4	Longint	6	0	2 <sup>32</sup>	TOTAL- DEC *	R
118	117	4	Longint	1	0	2 <sup>32</sup>	TEMP	R
120	119	4	Longint	-	0	0xFFFFFFFF	Actual Error	R
122	121	4	Longint	1	-10 <sup>7</sup>	10 <sup>7</sup>	External Temperature	R
124	123	4	Longint	3	0	2 <sup>32</sup>	External Pressure	R
126	125	4	Longint	3	0	2 <sup>32</sup>	FLOW ABS	R
128	127	4	Bool	-	0	1	FLOW SIGN	R

\*) The final number is given by the sum of the whole and the decimal. Example: Resulting Total measurement = (TOTAL) + (TOTAL DEC\*10<sup>-3</sup>).

### Flow

Unit: m<sup>3</sup>/h - it is not possible to change it. Real value = Actual value divided by 1000.

### TOTAL (TOTAL +, TOTAL -, AUX +)

Unit: m<sup>3</sup> – it is not possible to change it. Real value = Actual value divided by 1000.

### Temp

Temperature real value = Actual value divided by 10.

**Actual Error**

Actual error is represented in Hex format. For decode it has to be converted to binary format, where each bit represent specific error. (See MAGX2 manual, MAGX2 Error Code Table)

**External Temperature**

If external measurements module temperature is used then real temperature value = Actual value divided by 10.

**External Pressure**

If external measurements module pressure is used then real pressure value = Actual value divided by 1000.

**Flow ABS and SIGN**

In case signed value for longint cannot be used, a absolute value of flow and its sign can be used. Unit: m3/h - it is not possible to change it. Real ABS value = Actual value divided by 1000.

### 5.3 Float real-time measurement

Modbus register	Modbus address	No. of bytes	Data type	Description	Read/Write
150	149	4	Float	Float FLOW	R
152	151	4	Float	Float TOTAL	R
154	153	4	Float	Float AUX	R
156	155	4	Float	Float TOTAL+	R
158	157	4	Float	Float TOTAL-	R
160	159	4	Float	Float TEMP	R
162	161	4	Float	Float External Temperature	R
164	163	4	Float	Float External Pressure	R

#### Float Flow

Unit: m<sup>3</sup>/h - it is not possible to change it.

#### Float TOTAL (TOTAL +, TOTAL -, AUX +)

Unit: m<sup>3</sup> – it is not possible to change it.

#### Float Temp

Temperature.

#### Float External Temperature

When external measurements module temperature is used.

#### Float External Pressure

When external measurements module pressure is used.

## 5.4 Info

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
1000	999	4	Longint	0	-	-	Unit No.	R
1002	1001	4	Longint	0	-	-	Sensor Unit No.	R
1004	1003	4	Longint	0	-	-	Error [min]	R
1006	1005	4	Longint	0	-	-	OK [min]	R
1008	1007	4	Longint	0	-	-	Diameter [mm]	R
1010	1009	4	Longint	3	-	-	Flow Qn [m3/h]	R
1012	1011	4	Longint	2	-	-	FirmWare No.	R
1014	1013	4	Longint	0	-	-	Actual Error	R
1016	1015	4	Longint	0	-	-	FW Checksum	R
1018	1017	4	Longint	0	0	1	SD Card Present, 0=No, 1=Yes	R
1020	1019	4	Longint	0	0	1	GSM Module present, 0=No, 1=Yes	R
1022	1021	4	Longint	0	0	0xffffffff	GPRS IP Address	R
1024	1023	4	Longint	0	0	100	GSM Signal [%]	R
1026	1025	4	Longint	0	0	1	GPRS Module Present, 0=No, 1=Yes	R
1028	1027	4	Longint	0	0	1	Wi-Fi Module Present, 0=No, 1=Yes	R

**Unit no.** – unique number for each Flowmeter. If there are any problems, please refer to this number.

**Error [min]** – the number of minutes the device was measuring with some error.

**OK [min]** - the number of minutes that the device measured correctly.

**Diameter [mm]** – the nominal sensor diameter.

**Flow Qn [m3/h]** – nominal flow.

**Firmware No.** – this item shows the current firmware version

**Actual Error** - Actual error is represented in Hex format. For decode it has to be converted to binary format, where each bit represent each error. (See MAGX2 manual, MAGX2 Error Code Table).

**FW Checksum** – Validation of not allowed changes in FW (Metrological purposes)

**SD Card Present** – Value represent if SD card is present. (0 = not, 1 = is present).

**GSM Module present** - Value represent if GSM Module is present (0 = not, 1 = is present) [Reference 4].

**GPRS IP Address** - Actual IP address of GPRS module.

**GSM Signal** – Signal strength of GSM module [Reference 4].

**GPRS Module present** - Value represent if GSM Module is present (0 = not, 1 = is present)

**Wi-fi Module present** - Value represent if GSM Module is present (0 = not, 1 = is present)

## 5.5 Display

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/ Write
1500	1499	4	Longint	-	0	4	Unit Flow, 0=UKG/min, 1=USG/min, 2=m3/h, 3=l/min, 4=l/s	R/W
1502	1501	4	Longint	-	0	3	Unit Volume, 0=UKG, 1=USG, 2=m3, 3=l	R/W
1504	1503	4	Longint	-	0	1	Unit Temperature 0 = °C, 1 = °F	R/W
1506	1505	4	Longint	-	0	1	Unit Pressure 0 = bar, 1 = psi	R/W
1508	1507	4	Longint	-	0	4	Language, 0 = ENG, 1 = SPA, 2 = RUS, 3 = UKR, 4 = TUR	R/W
1510	1509	4	Longint	-	0	100	Contrast [%]	R/W
1512	1511	4	Longint	-	0	1	Backlight, 0 = 10 sec, 1 = Always on	R/W

**Unit Flow** – actual flow unit (default m<sup>3</sup>/h).

**Unit Volume** – totalizer unit (default m<sup>3</sup>).

**Unit Temperature** – applies for both internal and external temperature sensors.

**Language** – Language of transmitter menu.

**Contrast** – Set display's contrast.

**Backlight** – Set display's backlight behaviour.

## 5.6 User settings

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
2000	1999	4	Longint	-	0	10	Datalogger Interval, 0 = OFF, 1 = 1min, 2 = 5min, 3 = 10min, 4 = 15min, 5 = 30min, 6 = 1h, 7 = 2h, 8 = 6h, 9 = 12h, 10 = 24h	R/W
2002	2001	4	Longint	-	0	1	CSV Format, 0 = Coma (,), 1 = Semicolon (;)	R/W
2004	2003	4	Longint	-	0	1	Air Detector 0 = OFF, 1 = ON	R/W
2006	2005	4	Bool	-	0	1	Delete Auxiliary Volume?	R/W
2008	2007	4	Longint	0	1	120 (60)	Samples per Avg.	R/W
2010	2009	4	Longint	-	0	6	Current Loop Setting - Signal, 0 = Flow+, 1 = Flow-, 2 = Error, 3 = Air detector, 4 = Fixed, 5 = Direct driving, 6 = OFF	R/W
2012	2011	4	Longint	3	0	36 000	Flow min. [m3/h]	R/W
2014	2013	4	Longint	3	0	36 000	Flow max. [m3/h]	R/W
2016	2015	4	Longint	0	4	20	Current min. [mA]	R/W
2018	2017	4	Longint	0	4	20	Current max. [mA]	R/W
2020	2019	4	Longint	0	4	20	Current Loop Calibration point 1 [mA]	R/W
2022	2021	4	Longint	0	4	20	Current Loop Calibration point 2 [mA]	R/W
2024	2023	4	Longint	4	0.5	1.5	Current Loop Calibration const 1	R/W



2026	2025	4	Longint	4	0.5	1.5	Current Loop Calibration const 2	R/W
2028	2027	4	Longint	-	0	6	Voltage Output Setting - Signal, 0 = Flow+, 1 = Flow-, 2 = Error, 3 = Air detector, 4 = Fixed, 5 = Direct driving, 6 = OFF	R/W
2030	2029	4	Longint	3	0	36 000	Flow min. [m3/h]	R/W
2032	2031	4	Longint	3	0	36 000	Flow max. [m3/h]	R/W
2034	2033	4	Longint	0	0	10	Voltage min. [V]	R/W
2036	2035	4	Longint	0	0	10	Voltage max. [V]	R/W
2038	2037	4	Longint	-	0	9	Relay 1 Setting - Signal, 0 = OFF, 1 = Fixed, 2 = Flow+, 3 = Flow-, 4 = Error, 5 = Air Detect, 6 = On In, 7 = On Out, 8 = On<F1, 9 = On>F1	R/W
2040	2039	4	Longint	-	0	9	Relay 2 Setting - Signal, 0 = OFF, 1 = Fixed, 2 = Flow+, 3 = Flow-, 4 = Error, 5 = Air Detect, 6 = On In, 7 = On Out, 8 = On<F1, 9 = On>F1	R/W
2042	2041	4	Longint	3	0	36 000	Flow 1 [m3/h]	R/W
2044	2043	4	Longint	3	0	36 000	Flow 2 [m3/h]	R/W
2046	2045	4	Longint	3	0	36 000	Hysteresis 1 [m3/h]	R/W
2048	2047	4	Longint	3	0	36 000	Hysteresis 2 [m3/h]	R/W

2050	2049	4	Longint	-	0	8	Relay 3 Setting – Signal, 0 = OFF, 1 = ON, 2 = Flow+, 3 = Flow-, 4 = Error, 5 = Air Detect, 6 = Pulse/Litre+, 7 = Pulse/Litre-, 8 = Dosing	R/W
2052	2051	4	Longint	-	0	8	Relay 4 Setting – Signal, 0 = OFF, 1 = ON, 2 = Flow+, 3 = Flow-, 4 = Error, 5 = Air Detect, 6 = Pulse/Litre+, 7 = Pulse/Litre-, 8 = Dosing	R/W
2054	2053	4	Longint	0	0	99 999	Pulse / Litre + [I]	R/W
2056	2055	4	Longint	0	0	99 999	Pulse / Litre – [I]	R/W
2058	2057	4	Longint	0	0	99 999	Dose (Batch) [I]	R/W
2060	2059	4	Longint	-	0	6	Frequency Settings – Signal, 0 = OFF, 1 = Fixed, 2 = Flow+, 3 = Flow-, 4 = Error, 5 = Air Detect, 6 = Direct Driving	R/W
2062	2061	4	Longint	3	0	36 000	Flow 1 [m3/h]	R/W
2064	2063	4	Longint	3	0	36 000	Flow 2 [m3/h]	R/W
2066	2065	4	Longint	0	0	1 000	Frequency min [Hz]	R/W
2068	2067	4	Longint	0	0	1 000	Frequency max [Hz]	R/W
2070	2069	4	Longint	0	1	99	Duty Cycle [%]	R/W
2072	2071	4	Bool	-	0	1	Load Default Settings	R/W
2074	2073	4	Longint	0	0	9 999	User Password	R/W
2076	2075	4	Longint	0	0	247	Modbus Slave Address	R/W

2078	2077	4	Longint	0	0	3	Modbus Baudrate, 0 = 4800, 1 = 9600, 2 = 19200, 3 = 38400	R/W
2080	2079	4	Longint	0	0	3	Parity, 0 = Even, 1stopbit, 1 = Odd, 1stopbit, 2 = None, 2stopbits, 3 = None, 1stopbit	R/W
2082	2081	4	Longint	0	0	1	Totalizer Cycling, 0 = ON, 1 = OFF	R/W
2084	2083	4	Longint	5	0	50000	GSM Data Interval [min]	R/W
2086	2085	4	Longint	8	0	99999999	GSM Phone 1 High	R/W
2088	2087	4	Longint	8	0	99999999	GSM Phone 1 Low	R/W
2090	2089	4	Longint	8	0	99999999	GSM Phone 2 High	R/W
2092	2091	4	Longint	8	0	99999999	GSM Phone 2 Low	R/W
2094	2093	4	Longint	8	0	99999999	GSM Phone 3 High	R/W
2096	2095	4	Longint	8	0	99999999	GSM Phone 3 Low	R/W
2098	2097	4	Longint	-	0	1	GSM Empty Pipe Event, 0 = OFF, 1 = ON	R/W
2100	2099	4	Longint	-	0	1	GSM Zero Flow Event, 0 = OFF, 1 = ON	R/W
2102	2101	4	Longint	-	0	1	GSM Error Detect Event, 0 = OFF, 1 = ON	R/W
2104	2103	4	Longint	-	0	1	GSM Empty Pipe Event Settings, 0 = ON and OFF, 1 = Only ON	R/W
2106	2105	4	Longint	-	0	1	GSM Empty Pipe Event Settings, 0 = ON and OFF, 1 = Only ON	R/W
2108	2107	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay0	R/W
2110	2109	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay1	R/W

2112	2111	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay2	R/W
2114	2113	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay3	R/W
2116	2115	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay4	R/W
2118	2117	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay5	R/W
2120	2119	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay6	R/W
2122	2121	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay7	R/W
2124	2123	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay8	R/W
2126	2125	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay9	R/W
2128	2127	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay10	R/W
2130	2129	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay11	R/W
2132	2131	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay12	R/W
2134	2133	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay13	R/W
2136	2135	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay14	R/W
2138	2137	4	Longint	0	0	0xFFFFFFFF	GPRS_GateWay15	R/W
2140	2139	4	Longint	0	0	0xFFFFFFFF	GPRS_User0	R/W
2142	2141	4	Longint	0	0	0xFFFFFFFF	GPRS_User1	R/W
2144	2143	4	Longint	0	0	0xFFFFFFFF	GPRS_User2	R/W
2146	2145	4	Longint	0	0	0xFFFFFFFF	GPRS_Password0	R/W
2148	2147	4	Longint	0	0	0xFFFFFFFF	GPRS_Password1	R/W
2150	2149	4	Longint	0	0	0xFFFFFFFF	GPRS_Password2	R/W
2152	2151	4	Longint	0	0	1 024	GPRS_Port	R/W
2154	2153	4	Longint	0	0	9 999	GPRS_PIN	R/W
2156	2155	4	Longint	-	0	1	Wi-Fi AP mode	R/W

**Datalogger Interval** – this function selects how often data is written to the datalogger.

**CSV Format** – Set separator between each data. Set comma or semicolon.

**Air Detector** – this option allows selecting empty pipe check. Default OFF.

**Delete Aux + Volume** – write value different to zero for erasing the auxiliary flow totalizer.

**Samples per Avg.** – the number of samples that the flowmeter will use for calculation of its displayed average flow value. Default 15. (Maximal value for sensor v.8 and later is 120 and for sensor v.7 is 60)

**Current Loop Setting** - see chapter Current Loop in MAGX2 manual.

**Flow min** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Flow max** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current min** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current max** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current Loop Calibration point 1** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current Loop Calibration point 2** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current Loop Calibration constant 1** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Current Loop Calibration constant 2** - see chapter User Setting Menu - Current Loop in MAGX2 manual.

**Voltage output Setting** – see chapter User Setting Menu – Voltage Output in MAGX2 manual.

**Flow min** - see chapter User Setting Menu – Voltage Output in MAGX2 manual.

**Flow max** - see chapter User Setting Menu – Voltage Output in MAGX2 manual.

**Voltage min** - see chapter User Setting Menu – Voltage Output in MAGX2 manual.

**Voltage max** - see chapter User Setting Menu – Voltage Output in MAGX2 manual.

**Relay 1 setting** – see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Relay 2 setting** – see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Flow 1** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Flow 2** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Hysteresis 1** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Hysteresis 2** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Relay 3 setting** – see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Relay 4 setting** – see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Volume plus** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Volume minus** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Dose (Batch)** - see chapter User Setting Menu – Pulse Output in MAGX2 manual.

**Frequency setting** – see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Flow 1** - see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Flow 2** - see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Frequency 1** - see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Frequency 2** - see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Duty cycle** - see chapter User Setting Menu – Frequency Output in MAGX2 manual.

**Load default settings** – Load default factory setting or users changing setting on function Save setting.

**Password Setup** – Set password (user).

**Modbus Slave Address** – Modbus device address. Default 1

**Modbus Baudrate** – setup communication speed. Default 9600.

**Modbus Parity** – setup communication parameters. Default Even, 1 stopbit.

**Totalizer Cycling** – If set, each 3 seconds change totalizer on Main screen.

**GSM Data Interval** – For more info see GSM SMS Module Specification (chapter Set Sending Interval) [Reference 4].

**GSM Phone 1 H, GSM Phone 2 H, GSM Phone 3 H** – High part of phone number (i.e. 4207 for phone number +420777123456). Do not enter character +. The character + is added automatically. All phone numbers must be in international format (i.e. +420123456789). For more info see GSM SMS Module Specification [Reference 4].

**GSM Phone 1 L, GSM Phone 2 L, GSM Phone 3 L** – Low part of phone number (i.e. 77123456 for phone number +420777123456) [Reference 4].

**GSM Empty Pipe Event** – For more info see GSM SMS Module Specification [Reference 4].

**GSM Zero Flow Event** – For more info see GSM SMS Module Specification [Reference 4].

**GSM Error Detect Event** – For more info see GSM SMS Module Specification [Reference 4].

**GSM Empty Pipe Event Settings** – For more info see GSM SMS Module Specification [Reference 4].

**GSM Zero Flow Event Settings** – For more info see GSM SMS Module Specification [Reference 4].

**Wi-Fi AP mode** – For more info see Wi-Fi Module Specification

## 5.7 External Measurements

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
2500	2499	4	Longint	0	0	1	External temperature measurement state, 0 = ON, 1 = OFF	R/W
2502	2501	4	Longint	0	0	3	Temperature sensor type, 0 = PT100, 1 = PT200, 2 = PT500, 3 = PT1000	R/W
2504	2503	4	Longint	0	0	2	Temperature sensor connection, 0 = 2-Wire, 1 = 3-Wire, 2 = 4-Wire	R/W
2506	2505	4	Longint	1	0	1000	Temperature sensor calibration, actual temperature	R/W
2508	2507	4	Bool	0	0	1	Temperature sensor calibration, start now	R/W
2510	2509	4	Longint	0	0	1	External pressure measurement state, 0 = ON, 1 = OFF	R/W
2512	2511	4	Longint	0	4	20	Current min. [mA]	R/W
2514	2513	4	Longint	0	4	20	Current max. [mA]	R/W
2516	2515	4	Longint	3	0	9999999	Pressure min [mbar]	R/W
2518	2517	4	Longint	3	0	9999999	Pressure max [mbar]	R/W

**External temperature measurement state** – Switches on/off the external temperature module.

**Temperature sensor type and connection** – defines which and how is the external temperature sensor connected. For more information follow MAGX2 manual (Reference 3).

**Temperature sensor calibration temperature and start now** - set the known temperature \* 10 to actual temperature register and write 1 to start now.

**External pressure measurement state** – Switches on/off the external pressure module.

**External pressure current loop calibration** – defines input current span that is equal to measured pressure.

## 5.8 Service Settings

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
3000	2999	4	Bool	-	0	1	Error Delete?	R/W
3002	3001	4	Bool	-	0	1	OK Delete?	R/W
3004	3003	4	Bool	-	0	1	Delete Volume (-)?	R/W
3006	3005	4	Bool	-	0	1	Delete Volume (+)?	R/W
3008	3007	4	Bool	-	0	1	Delete Volume Total?	R/W
3010	3009	4	Longint	0	0	1	Flow simulation, 0=ON, 1=OFF	R/W
3012	3011	4	Longint	3	0	36 000 000	Simulated flow [m3/h]	R/W
3014	3013	4	Longint	-	0	1	Service Mode, 0=ON, 1=OFF	R/W
3016	3015	4	Longint	-	0	1	Measurement, 0 = Run, 1 = Stop	R/W
3018	3017	4	Longint	3	0	0,999	Air Constant	R/W
3020	3019	4	Longint	0	0	120	Start Delay [s]	R/W
3022	3021	4	Longint	-	0	1	Invert Flow, 0 = No-invert, 1 = Invert	R/W
3024	3023	4	Longint	0	0	2	Electrode Cleaning, 0 = OFF, 1 = ON, 2 = ON Start	R/W
3026	3025	4	Longint	0	1	9999	Clean Time [s]	R/W
3028	3027	4	Bool	-	0	1	Start Now?	R/W
3030	3029	4	Longint	-	0	5	Low Flow Cutoff, 0 = 0.5%, 1 = 1%, 2 = 2%, 3 = 5%, 4 = 10%, 5 = OFF	R/W
3032	3031	4	Longint	3	0	36 000	Flow Qn [m3/h]	R/W



3034	3033	4	Longint	0	0	31 129 999	Date Settings	R/W
3036	3035	4	Longint	0	0	235 959	Time Settings	R/W

**Delete Error (min)** – write value different to zero for erasing the Error min counter.

**Delete OK (min)** – write value different to zero for erasing the OK min counter.

**Delete Total – Volume** – write value different to zero for erasing the Total – flow totalizer.

**Delete Total + Volume** – write value different to zero for erasing the Total + flow totalizer.

**Delete Total Volume** – write value different to zero for erasing the Total flow totalizer.

**Flow Simulation** – switch off/on the simulation flow function. Default OFF.

**Simulated Flow** – write simulated flow.

**Service Mode** – write value different to zero for turn ON the service mode. Default OFF.

**Measurement** – 0 = Stop – the unit shows actual flow, but the totalizers are stopped.  
1 = Running – totalizers are active. Default Stop.

**Air Constant** – constant value to determine the Empty pipe detection limit. Default 188.

**Start Delay** – Value represent how long is stabilize all component. (actual flow is “0” at this time).

**Invert Flow** – this function serves to change the direction of the flow. Default No-invert.

**Electrode Cleaning** – Set electrode cleaning

**Clean Time** – number of seconds, how long run electrode cleaning, when select “On Start” or “Start Now”

**Start Now?** – If set, start electrode cleaning now for Clean Time.

**Low Flow Cutoff** – this function serves to set the minimum flow the flowmeter will react on. Default 2%.

**Flow Qn** – set nominal flow (automatic set if changing the diameter).

**Date Settings** - date write in BCD format YYYYMMDD (i.e. 25.03.2010 = (hex)0x20100325)

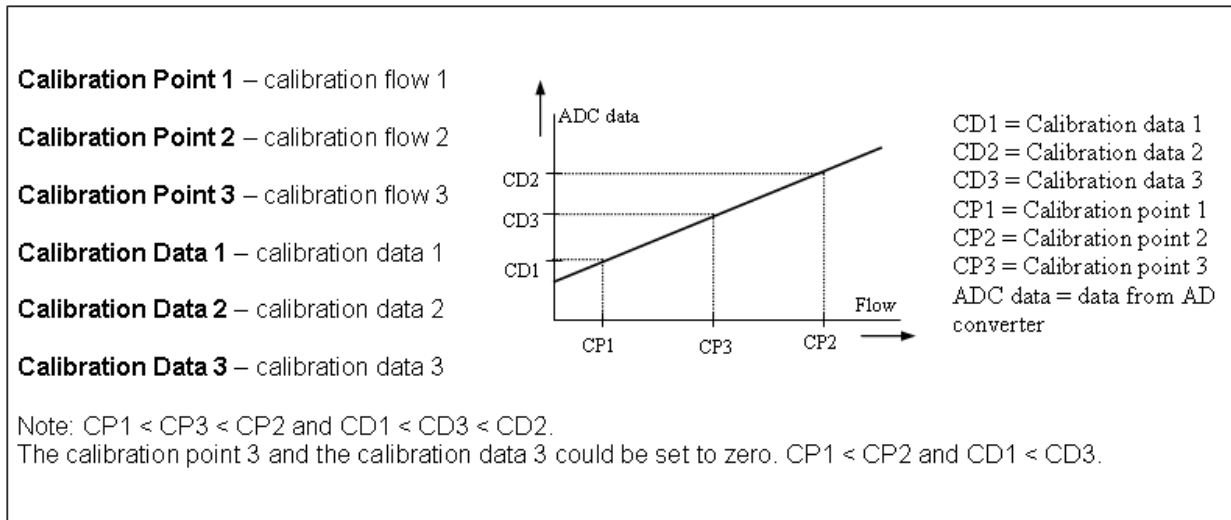
**Time Settings** - time write in BCD format HHMMSS (i.e. 08:33:15 = (hex)0x00083315)

## 5.9 Factory Settings

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
4000	3999	4	Longint	0	10	1 000	L = Diameter	R/W
4002	4001	4	Longint	0	0	9 999 999	Unit No.	R/W
4004	4003	4	Longint	3	0.015	36 000 000	Calibration Point1	R/W
4006	4005	4	Longint	3	0.015	36 000 000	Calibration Point2	R/W
4008	4007	4	Longint	3	0.015	36 000 000	Calibration Point3	R/W
4010	4009	4	Longint	0	-10000000	10000000	Calibration Data1	R/W *
4012	4011	4	Longint	0	-10000000	10000000	Calibration Data2	R/W *
4014	4013	4	Longint	0	-10000000	10000000	Calibration Data3	R/W *
4016	4015	4	Bool	-	0	1	Zero Flow?	R/W
4018	4017	4	Longint	0	-10000000	10000000	Zero Flow Constant	R/W
4020	4019	4	Bool	-	0	1	Zero Flow Erase?	R/W
4022	4021	4	Longint	-	0	1	Excitation frequency, 0=3.125Hz, 1=6.250Hz	R/W
4024	4023	4	Longint	-	0	1	Excitation, 0=ON, 1=OFF	R/W
4026	4025	4	Longint	-	0	1	Service Mode, 0=ON, 1=OFF	R/W
4028	4027	4	Bool	-	0	1	Save Settings?	R/W
4030	4029	4	Longint	0	0	99999999	Sensor communication module SN	R/W
4048	4047	4	Longint	0	0	100	Optical Buttons Down/Up Level	R/W
4050	4049	4	Longint	0	0	100	Optical Buttons Left/Right Level	R/W
4052	4051	4	Longint	0	0	100	Optical Buttons Enter/ESC Level	R/W

**Diameter** – diameter of the sensor.

**Unit No.** – set serial number of the unit



**Zero Flow?** – after activation this function, average value from ADC converter ( number of samples for average is value of Samples per Average).

**Zero Flow Constant** – Set manually value for zero flow constant.

**Zero Flow Erase** – erase zero flow constant.

**Excitation Frequency** – choose the excitation frequency.

**Excitation** – write zero for turn OFF the excitation. Default ON.

**Service Mode** – write value different to zero for turn ON the service mode. Default OFF.

**Save Settings?** – Save setting to battery backed up RAM, next time will be load with Load Default Settings function.

**Sensor communication module SN** – Serial number of connected sensor communication module v8, 9

**Optical buttons x/x level** – sets level of sensitivity 0-100%. Higher number less sensitive buttons.

## 5.10 Authorize

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
5000	4999	4	Longint	0	0	9 9999999	User Password Setup	R/W

**Password Setup** – Set password (user).

## 5.11 Datalogger

Modbus register	Modbus address	No. of bytes	Data type	No. of decimal	Min Value	Max Value	Description	Read/Write
10000	9999	4	Longint	0	0	99991231	Request Date	R/W
10002	10001	4	Longint	0	0	235959	Request Time	R/W
10004	10003	4	Longint	0	0	235959	Datalogger Date	R
10006	10005	4	Longint	0	0	235959	Datalogger Time	R
10008	10007	4	Longint	0	0	235959	Total + DIG	R
10010	10009	4	Longint	0	0	235959	Total + DEC	R
10012	10011	4	Longint	0	0	235959	Total – DIG	R
10014	10013	4	Longint	0	0	235959	Total – DEC	R
10016	10015	4	Longint	0	0	235959	Error min	R
10018	10017	4	Longint	0	0	235959	Error	R

**Request Date** – Date which is needed to read from datalogger

**Request Time** – Time which is needed to read from datalogger

**Datalogger Date** – date of datalogger record

**Datalogger Time** – time of datalogger record

**Total + DIG** – Positive totalizer integral fraction

**Total + DEC** – Positive totalizer decimal fraction (always 3 decimal numbers, i.e.: 25 = 0.025)

**Total – DIG** – Negative totalizer integral fraction

**Total – DEC** – Negative totalizer decimal fraction (always 3 decimal numbers, i.e.: 25 = 0.025)

**Error min** – the number of minutes the device was not measuring because of errors.

**Error** – Error code, for decode see MAGX2 manual.

## 6. Contact



Technical support: [support@arkon.co.uk](mailto:support@arkon.co.uk)

Skype: support.arkon

Sales office: [office@arkon.co.uk](mailto:office@arkon.co.uk)

Office hours:

8:30 – 18:00 (GMT+1)

Direct technical support:

8:00 – 16:30 (GMT+1)